Tuning:
- Hard to change gains during program runtime.

Command and Control Interface:
- Using Terminals: Confusing
- No software kill switch
- Hard to track running nodes

Unified GUI
- Easy to use
- Safety buttons implemented
- Node status menu
- Ability to populate other plugins in the same window.

Altitude hold mode:
- A new flight mode that uses sonar and barometer sensors was implemented for altitude control.

Acknowledgements
- We would like to express our gratitude towards Dey, Matt, Shaurya, Drew and Martial for their guidance and support.
- Our thanks are extended to all those who made RISS possible.

References