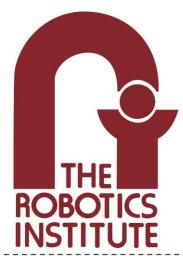
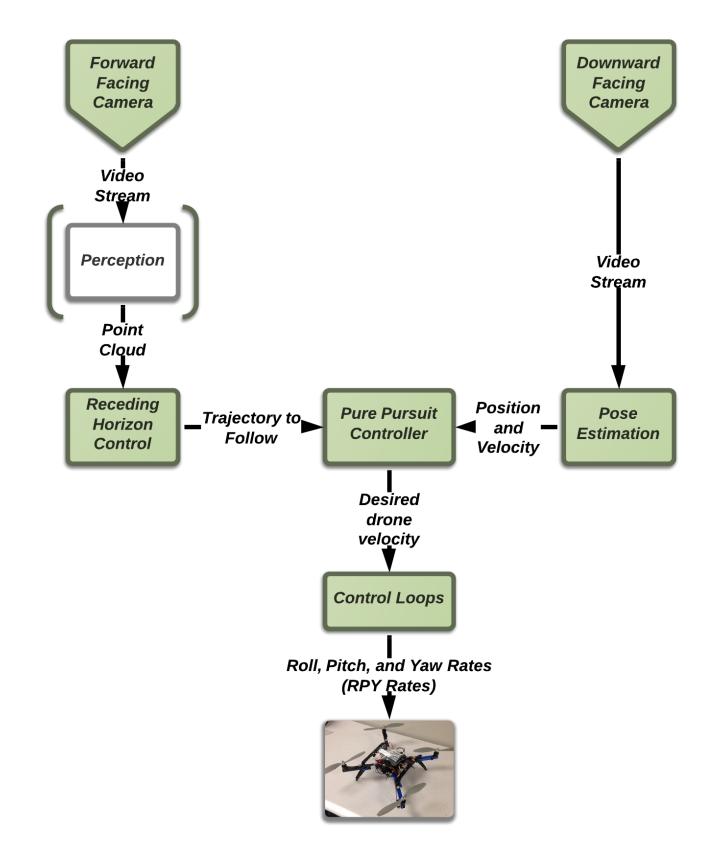
Monocular Visual Features for Fast Flight Through Forests Christopher Eriksen, Advisor: Drew Bagnell

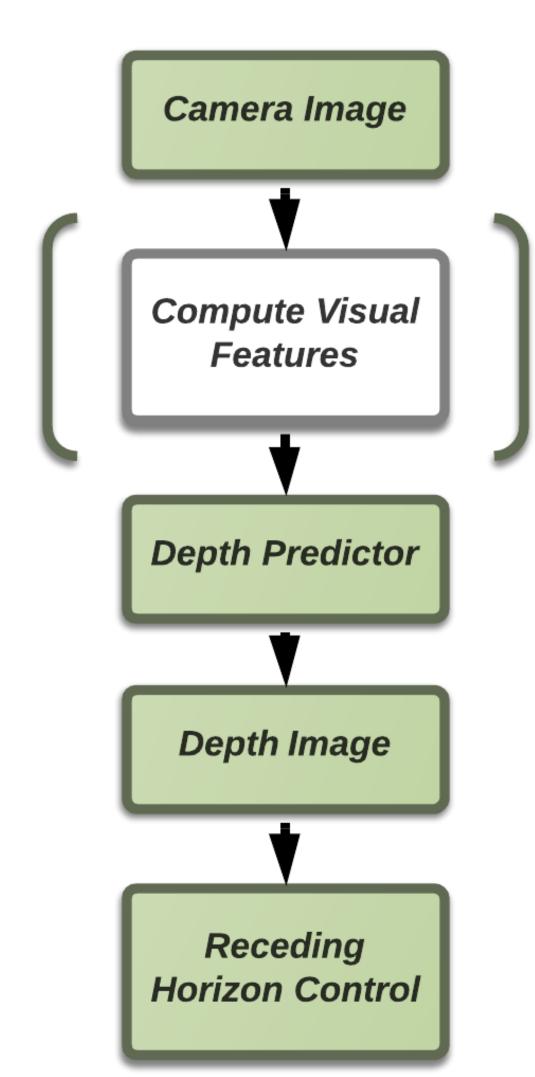


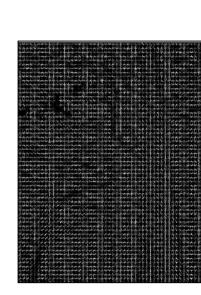
Motivation



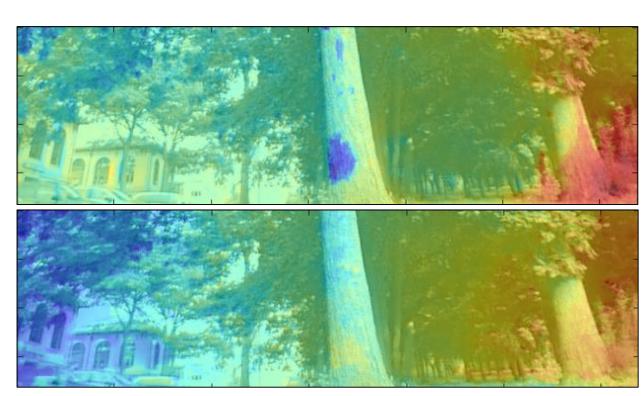


Perception Pipeline





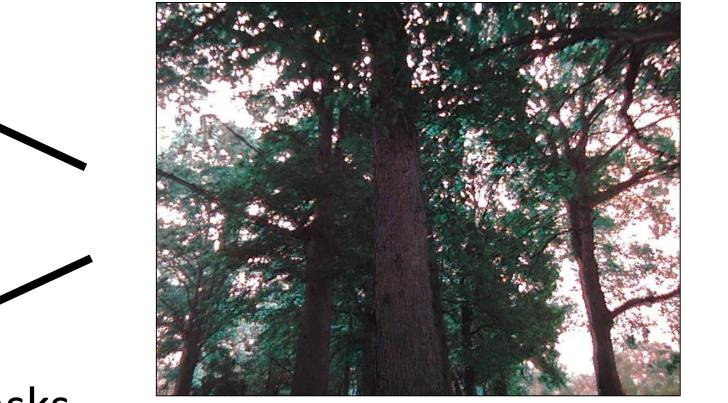


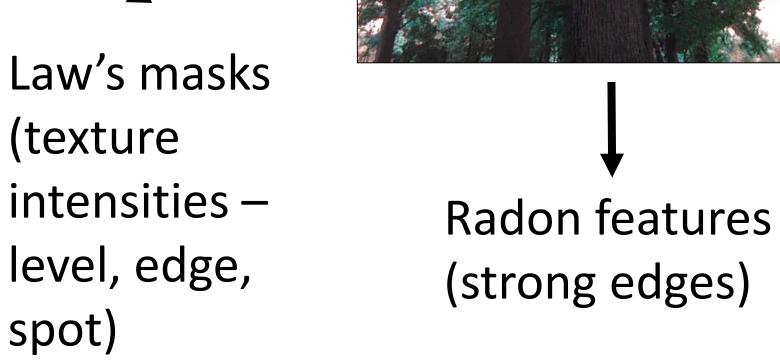




Monocular Features for Depth Prediction

Histogram of Oriented Gradients (texture)



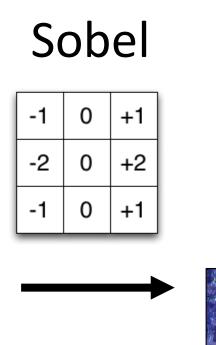


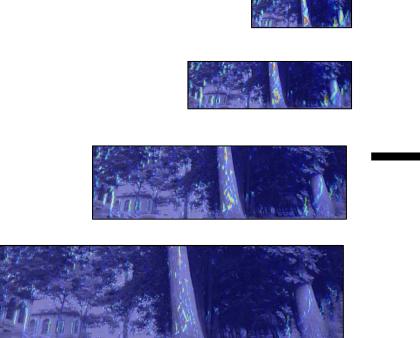
Optical Flow and Looming

X Flow

(texture

spot)



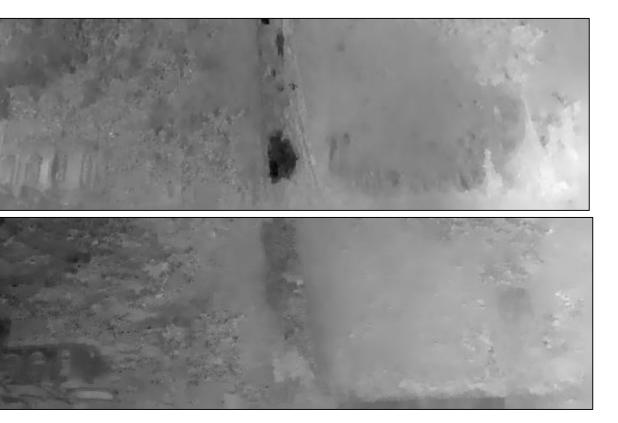


Y Flow

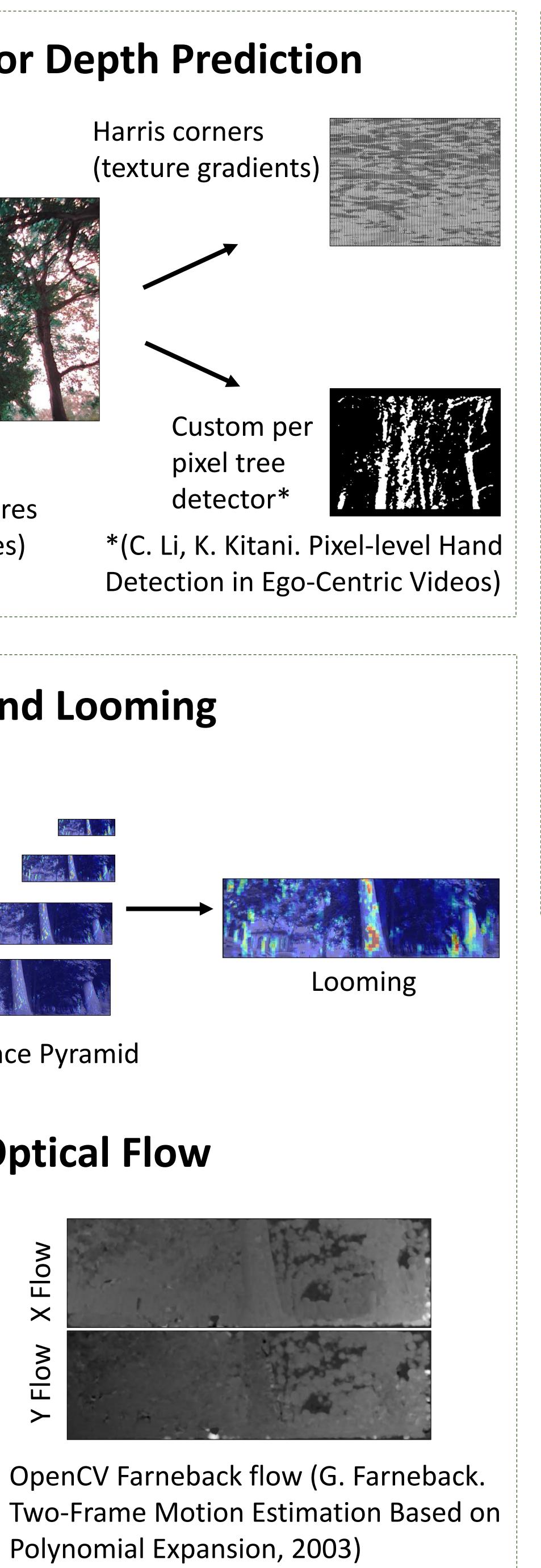
Divergence Pyramid

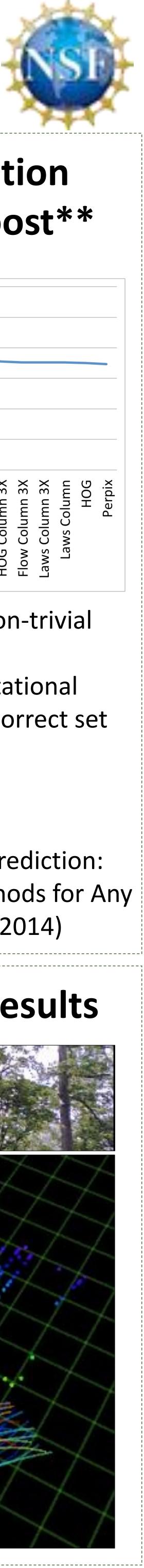
High Fidelity Optical Flow

V.S.

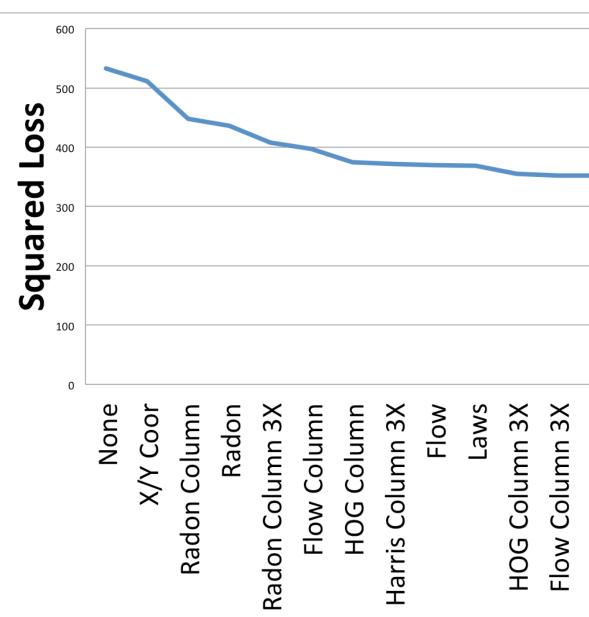


TV regularization flow (M. Werlberger. **Convex Approaches for High** Performance Video Processing, 2012)





Feature Selection Using SpeedBoost**



- Each feature has a non-trivial computational cost
- Given a total computational budget, what is the correct set of features to use?

****(A. Grubb. Anytime Prediction:** Efficient Ensemble Methods for Any Computational Budget, 2014)

Preliminary Results

