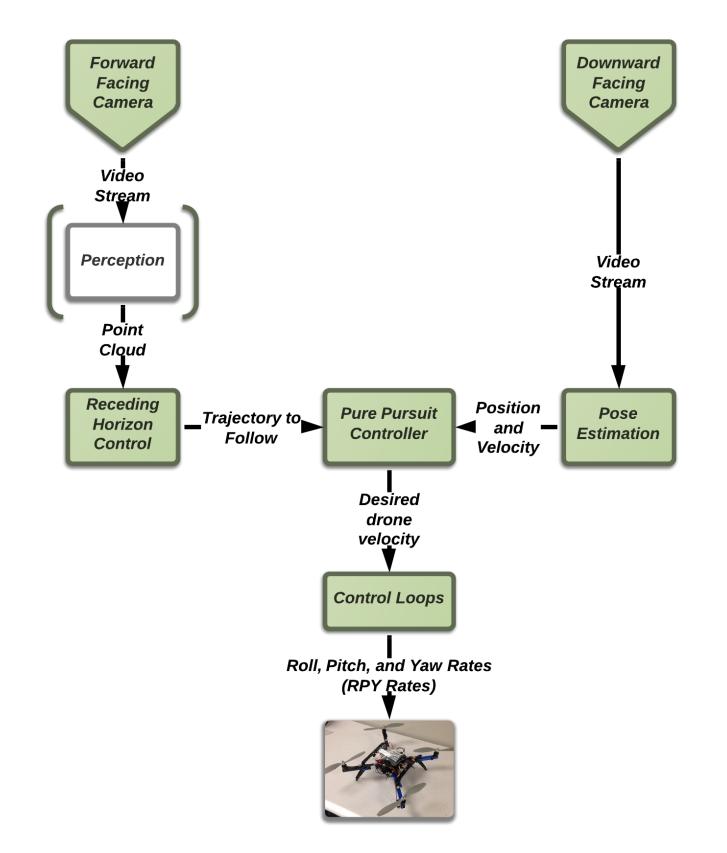
# **Monocular Visual Features for Fast Flight Through Forests** Christopher Eriksen, Advisor: Drew Bagnell

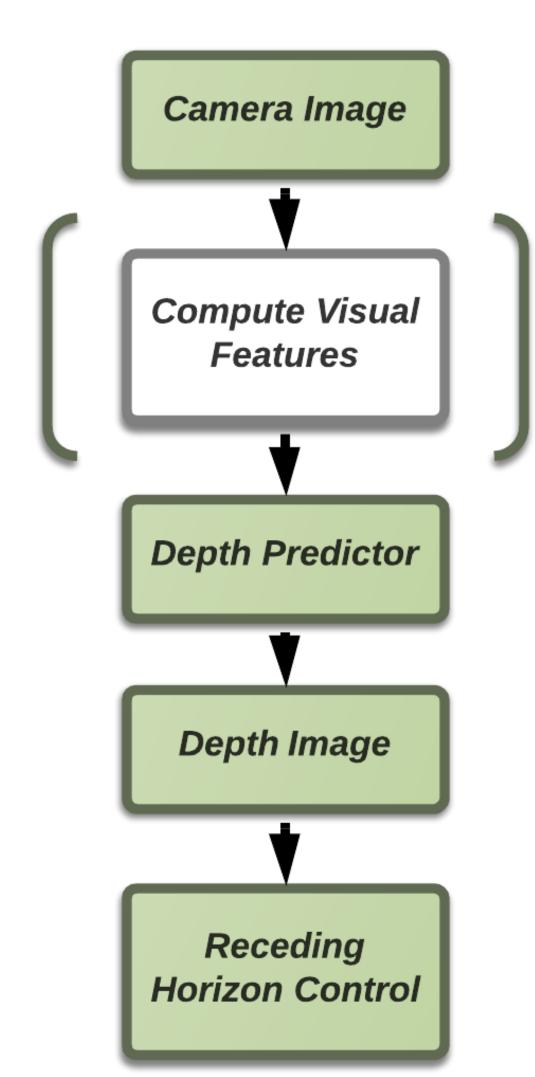


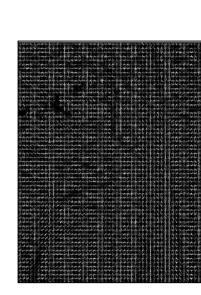
#### Motivation



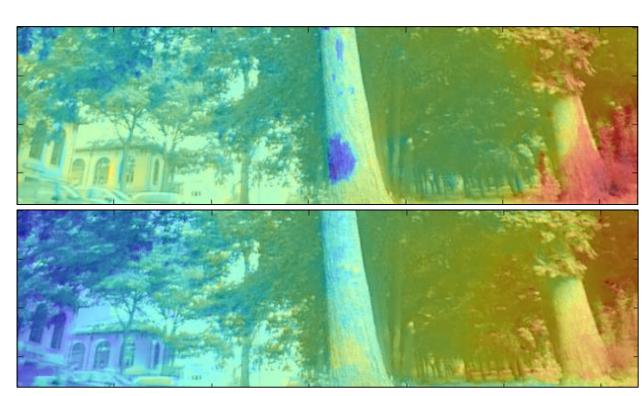


#### **Perception Pipeline**





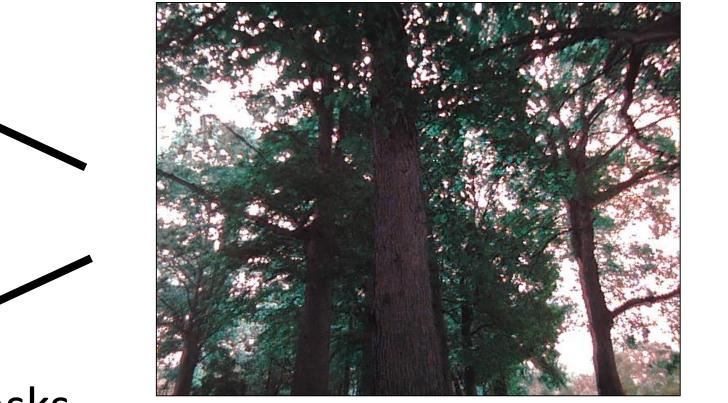


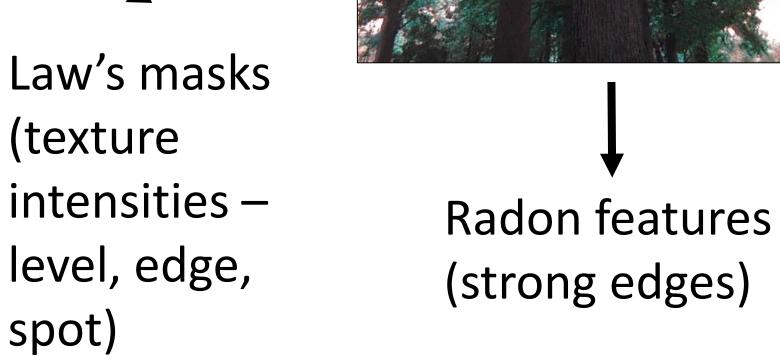




## **Monocular Features for Depth Prediction**

Histogram of Oriented Gradients (texture)



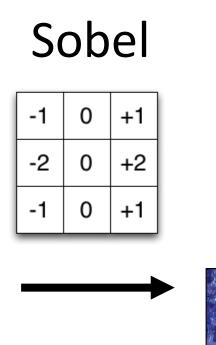


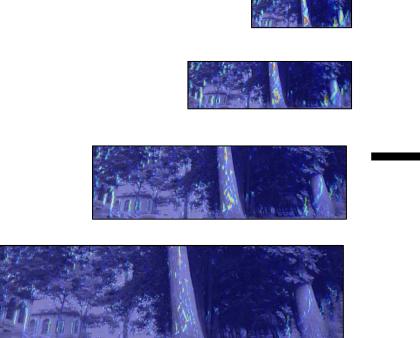
# **Optical Flow and Looming**

X Flow

(texture

spot)



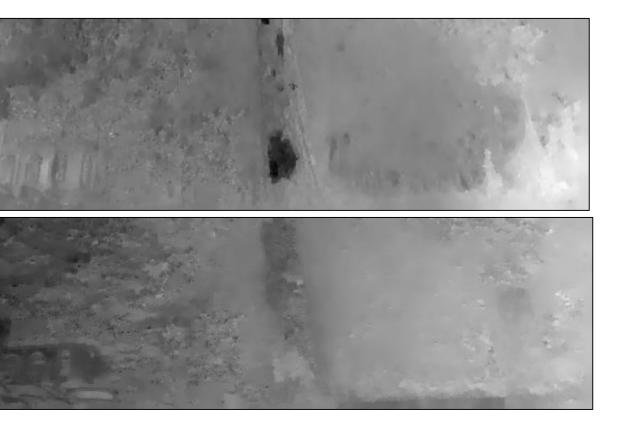


Y Flow

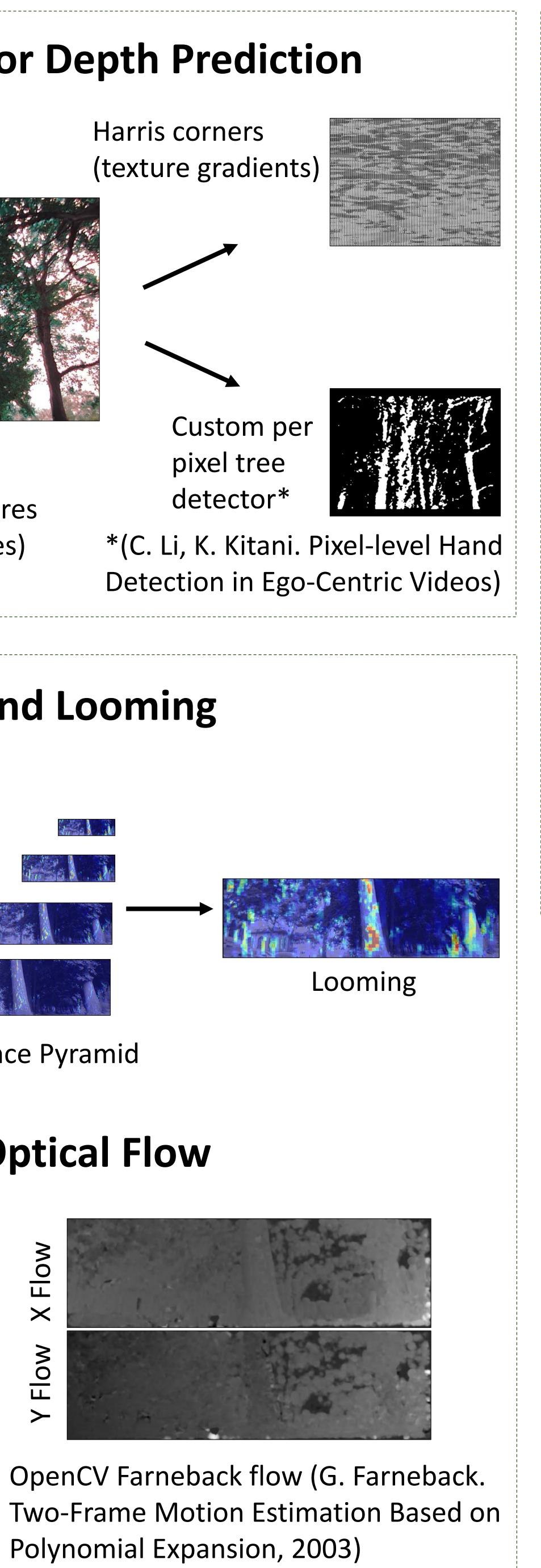
Divergence Pyramid

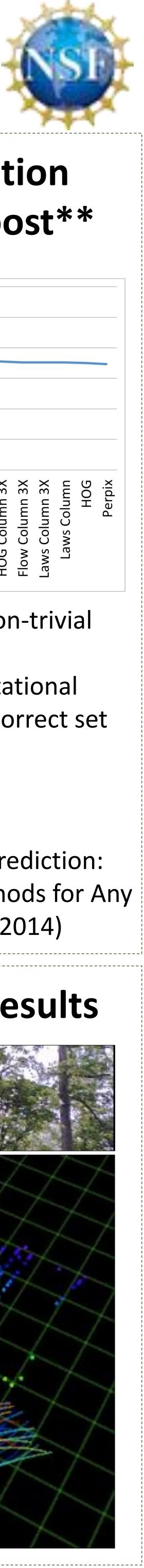
# **High Fidelity Optical Flow**

V.S.

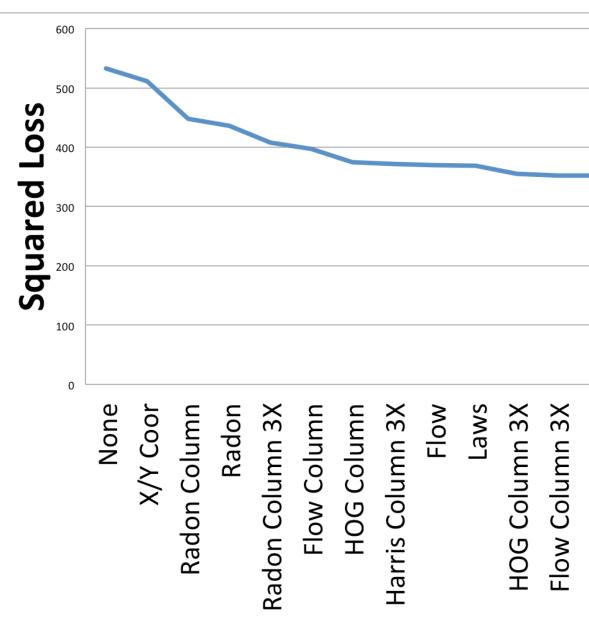


TV regularization flow (M. Werlberger. **Convex Approaches for High** Performance Video Processing, 2012)





## **Feature Selection** Using SpeedBoost\*\*



- Each feature has a non-trivial computational cost
- Given a total computational budget, what is the correct set of features to use?

**\*\*(A. Grubb. Anytime Prediction:** Efficient Ensemble Methods for Any Computational Budget, 2014)

# **Preliminary Results**

